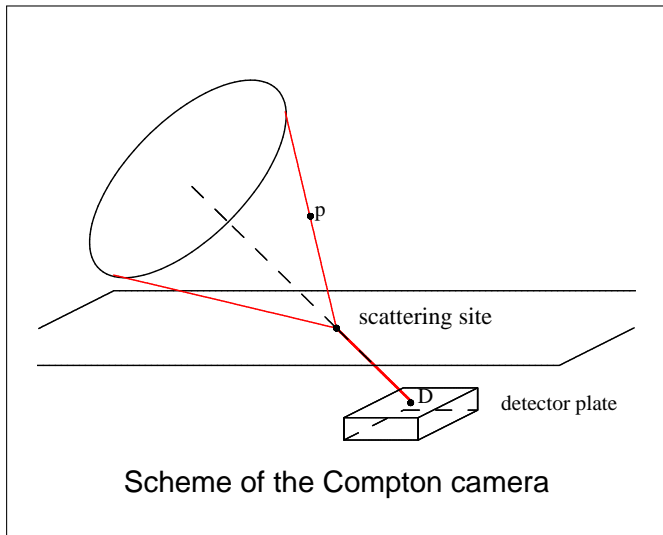


New reconstructions from cone Radon transform

Victor Palamodov
Tel Aviv University

March 30, 2017

- Trajectories of single-scattered photons with fixed income and outcome energies in Compton camera form a cone of rotation:



- A spherical cone in an Euclidean space E^3 with apex at the origin can be written in the form

$$C(\lambda) = \{x \in E^3 : \lambda x_1 = s\}, \quad s = \sqrt{x_2^2 + x_3^2}.$$

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- The integral

$$g_C(y) = \cos \psi \int_{x \in C(\lambda)} f(y+x) w(x) dx_2 dx_3, \quad y \in E^3$$

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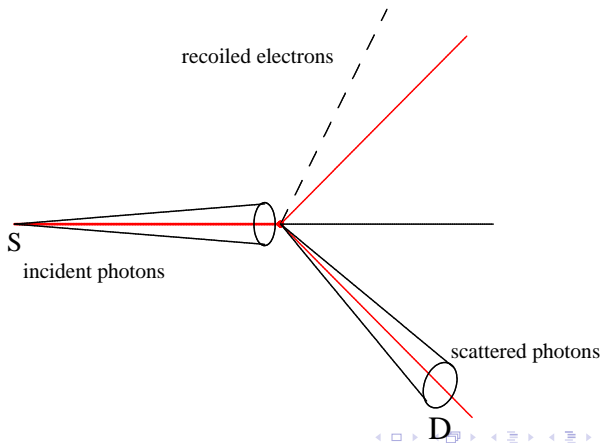
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- Analytic inversion of the regular and singular monochrome (one opening) cone Radon transforms is in the focus of this talk.

Single-scattering tomography

- The realistic model (SPSF) for single-scattering optical tomography based on the photometric law of scattered radiation modeled by the singular cone transform.



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(many openings)

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- Jung and Moon 2016 proposed the scheme for collecting non redundant data from a line of detectors and rotating axis.

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- Gouia-Zarrad and Ambartsoumian 2014 found the reconstruction formula for the regular cone transform in the half-space with free apex.

Cone transform with free apex

- Cone Radon integral equation can be written in the convolution form

$$g = |x|^{-k} \delta_{-C} * f, \quad (1)$$

where

$$\begin{aligned} \delta_{-C}(\varphi) &= \int_C \varphi dS = \cos^{-1} \psi \int \int \varphi(-\lambda s, x_2, x_3) dx_2 dx_3, \\ s &= \sqrt{x_2^2 + x_3^2}. \end{aligned}$$

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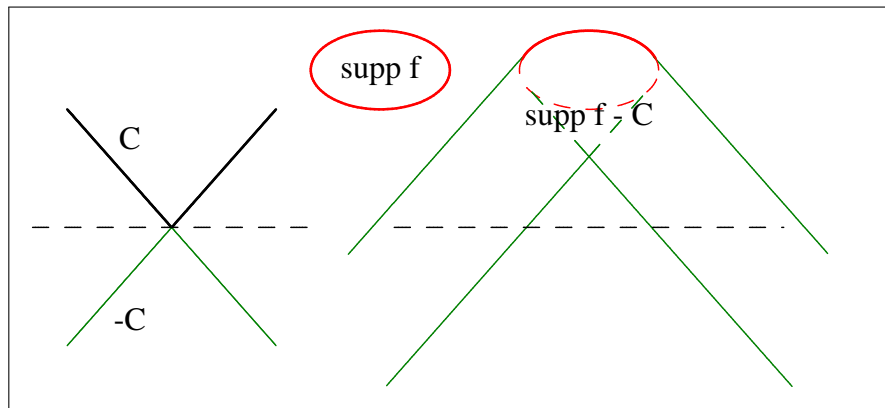
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- The solution f of (1) defined on $\{x_1 \geq 0\}$ is unique if it vanishes for $x_1 > m$ for some $m > 0$.
- We focus on the case $n = 3$ and use the notations

$$\Delta_0 = \delta_{-C}, \quad \Delta_1 = |x|^{-1} \delta_{-C}.$$

Support of the convolution

- For a function f on E^n vanishing for $x_1 > m$ for some m , the convolution $g = \Delta_k * f$ is well defined and $\text{supp} \Delta_k * f \subset \text{supp} f - C$.



Inversion of regular transforms

- **Case** $k = 0$. The solution of

$$\Delta_0 * f_0 = g_0,$$

can be found in the form

$$f_0(x) = \frac{1}{2\pi \cos^3 \psi} \square^2 \Delta_1 * \Theta_1 * g_0 \quad (2)$$

$$= \frac{1}{2\pi \cos^3 \psi} \square^2 \int_{t \in C} \left(\int_{x_1}^{\infty} g_0(y - t_1, x_2 - t_2, x_3 - t_3) dy \right) \frac{dS}{|t|}$$

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and

- $$\square = \frac{\partial^2}{\partial x_1^2} - \lambda^2 \left(\frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial x_3^2} \right).$$

- **Case** $k = 1$. *The solution of*

$$\Delta_1 * f_1 = g_1 \quad (3)$$

reads

$$\begin{aligned} f_1(x) &= \frac{1}{2\pi \cos^3 \psi} \square^2 \Delta_0 * \Theta_1 * g_1 \quad (4) \\ &= \frac{1}{2\pi \cos^3 \psi} \square^2 \int_{t \in C} \int_{x_1}^{\infty} g_1(y - t_1, x_2 - t_2, x_3 - t_3) dy dS. \end{aligned}$$

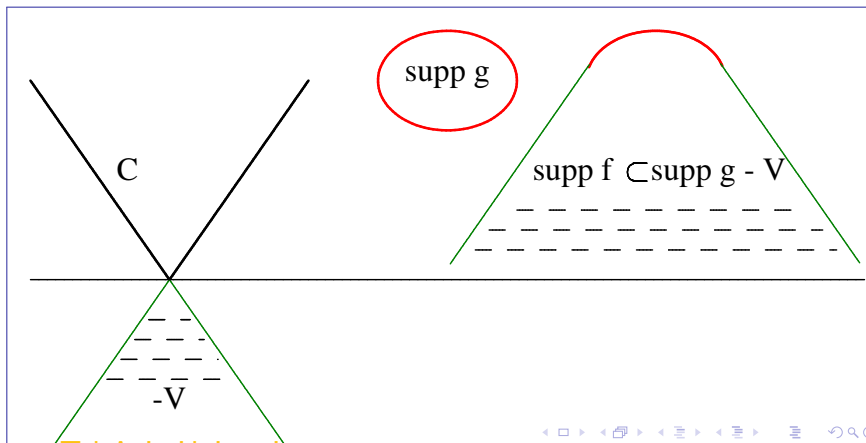
Conclusion: Inversion of any of two regular cone transform is given by the another cone transform followed (or preceded) by the 4 order differential operator and additional integration from x_1 to ∞ in the vertical variable. No Fourier transform etc. is necessary.

Support of the solution

- **Corollary** For any function f with support in E_m for some m , we have

$$\text{supp } f \subset \text{supp } \Delta_k * f - V, \quad k = 0, 1$$

where V is the convex hull of C .



- Distributions Δ_0 and Δ_1 are homogeneous of order 2 and 1. Fourier transforms are equal to (V.P. 2016, P.140)

$$\hat{\Delta}_0(p) = -\frac{1}{2\pi \cos^2 \psi} |p_1| (p_1^2 - \lambda^2 (p_2^2 + p_3^2))^{-3/2},$$

$$\hat{\Delta}_1(p) = -\frac{2i}{\cos \psi} \operatorname{sgn} p_1 (p_1^2 - \lambda^2 (p_2^2 + p_3^2))^{-1/2}$$

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- Both have analytical continuation at $H_+ = \{p \in \mathbb{C}^3 : \operatorname{Im} p_1 \geq 0\}$.

- The above calculations results

$$2\pi i \cos^3 \psi (p_1 + i0)^{-1} (p_1^2 - \lambda^2 (p_2^2 + p_3^2))^2 \hat{\Delta}_0(p) \hat{\Delta}_1(p) = 1$$

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- Calculating the inverse Fourier transform we obtain

$$F^{-1} (p_1^2 - \lambda^2 (p_2^2 + p_3^2)) = -\frac{1}{4\pi^2} \square \delta_0,$$

and

$$F^{-1} (p_1 + i0)^{-1} = -2\pi i \Theta_1,$$

where $\Theta_1 = \theta(x_1) \delta_0(x_2, x_3)$, $\theta(t) = 1$ for $t < 0$ and $\theta(t) = 0$ for $t > 0$.

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- Finally

$$\cos^3 \psi \square^2 \delta_0 * \Theta_1 * \Delta_1 * \Delta_0 = \delta_0, \quad (5)$$

where the convolutions of distributions Θ_1 , Δ_1 and $\square^2 \delta_0$ are well defined and commute.

- Applying (5) to f_0 gives

$$f_0 = \cos^3 \psi \square^2 * \Delta_1 * \Theta_1 * \Delta_0 * f_0 = \cos^3 \psi \square^2 * \Delta_1 * \Theta_1 * g_0$$

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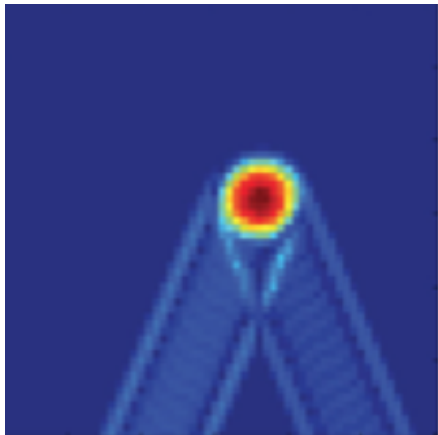
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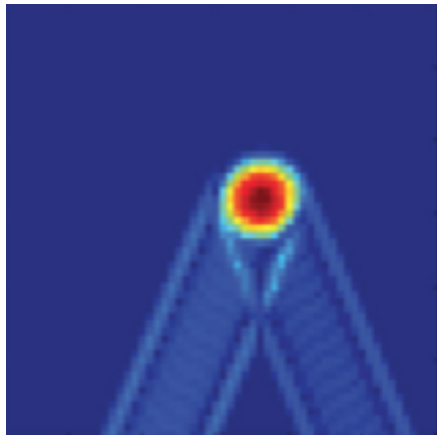
and (4) follows.

- **Remark 1.** Constant attenuation can be included in this method.

- **Remark 2.** Solution of (1) could be done in form $\hat{g}(p) / \hat{\Delta}_k(p)$ in the frequency domain. Implementation of this method supposes cutting out the "plumes" of g which causes the artifacts in the reconstruction as in the following picture



- **Remark 2.** Solution of (1) could be done in form $\hat{g}(p) / \hat{\Delta}_k(p)$ in the frequency domain. Implementation of this method supposes cutting out the "plumes" of g which causes the artifacts in the reconstruction as in the following picture



- which is due to the courtesy of Gouia-Zarrad, Ambartsoumian 2014.

Inversion of the singular cone transform

- Fix $\lambda > 0$ and consider the singular integral transform

$$G(q, \theta) = \int_{C_\lambda(\theta)} f(q+x) \frac{dS}{|x|^2}, \quad \theta \in S^2, \quad q \in E^3, \quad (6)$$

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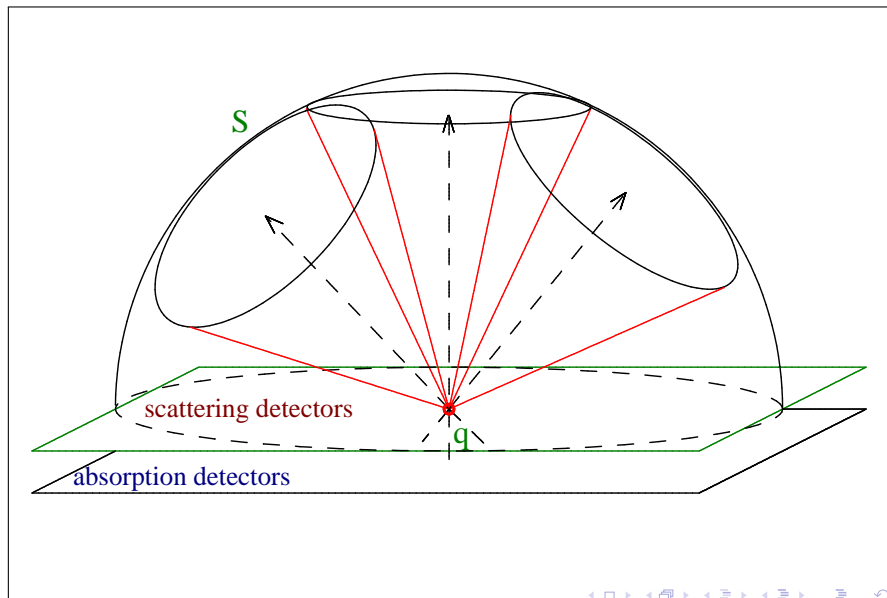
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 - (ii) for any point $q \in Q$, there exists a unit vector $\theta(q)$ such that $\text{supp} f \subset q + C_\lambda(\theta(q))$.

Compton cones with swinging axis



- **Step 1.** The singular ray transform

$$Xf(q, \xi) = \int_0^\infty f(q + r\xi) \frac{dr}{r}, \quad \xi \in S^2, q \in Q \quad (7)$$

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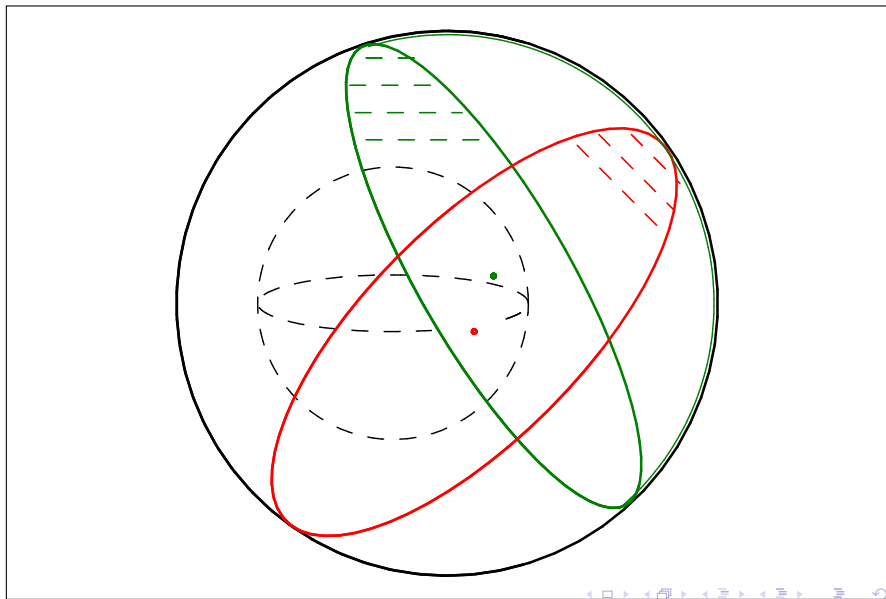
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- The planes containing these circles are tangent to the central ball B of radius $\rho = (1 + \lambda^2)^{-1/2}$.

Step 2: Nongeodesic Funk transform



- **Theorem** For any ρ , $0 \leq \rho < 1$, $\alpha \in E$, $|\alpha| \leq 1$, an arbitrary function $g \in C^2(S^2)$ can be reconstructed from data of integrals

$$\Gamma(\theta) = \int_{\zeta \in S^2, \langle \zeta - \alpha, \theta \rangle = \rho} g(\zeta) d\sigma, \quad \theta \in S^2 \quad (8)$$

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- The singular integral is regularized as follows

$$\int_{S^2} \frac{\Gamma(\theta)}{\left(\langle \xi - \alpha, \theta \rangle - \rho \right)^2} dS = -\Delta(\theta) \int_{S^2} \Gamma(\theta) \log \left(\langle \xi - \alpha, \theta \rangle - \rho \right) dS.$$

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- The reconstruction from spherical integrals (8) on S^n was stated in V.P. 2016 for arbitrary n , $0 \leq \rho < 1$, $|\alpha| \leq 1$.

- **Step 3.** By (i) formula (9) can be applied to $\Gamma(q, \theta)$ for $\alpha = 0$, $\rho = (1 + \lambda^2)^{-1/2}$ which provides the reconstruction of $g(q, \xi) = Xf(q, \xi)$ for any $q \in Q$ and all ξ .

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which yields (by Grangeat's method) for any p ,

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- where the left hand side can be calculated from Xf .

- **Step 4** By (ii) we can use the Lorentz-Radon formula for any $x \in \text{supp}f$,

$$\begin{aligned}
 f(x) &= -\frac{1}{8\pi^2} \int_{\omega \in S^2} \frac{\partial^2}{\partial p^2} \int_{\langle \omega, q-x \rangle = 0} f(q) \, dq d\Omega \\
 &= -\frac{1}{8\pi^2} \int_{\omega \in S^2} \int_{\langle \omega, \xi \rangle = 0} \langle \omega, \nabla_{\xi} \rangle^2 \chi f(q(\omega), \xi) \, d\varphi d\Omega
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- This completes the reconstruction of f .

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- **Theorem** For any function $f \in C_0^2(E^3)$ and any $x \in \text{supp } f \setminus \Gamma$ such that any plane P through x meets Γ , the equation holds

$$\begin{aligned} f(x) &= -\frac{1}{32\pi^4} \int_{y \in \Gamma} \int_{\langle y-x, \xi \rangle = 0} \partial_s^2 \frac{\varepsilon(y, \xi)}{|y-x|} ds \\ &\quad \times \int_{\langle \xi, \nu \rangle = 0} \langle \xi, \nabla_\nu \rangle^2 \partial_s g(y, \nu) d\theta d\varphi. \end{aligned}$$

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